

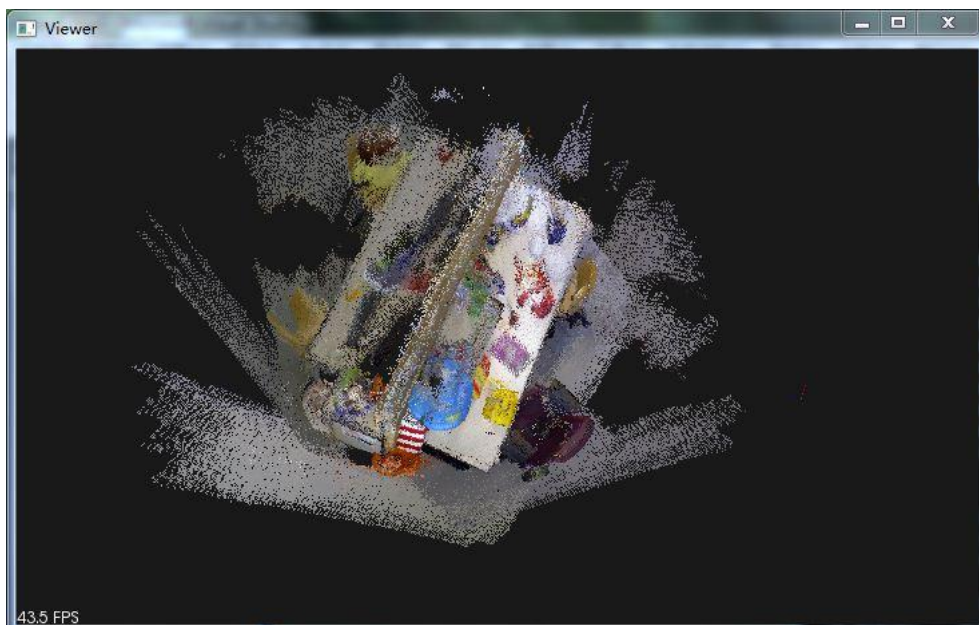
## 定量实验结果

用到 RGBD SLAM 数据集 (rgbd\_dataset\_freiburg3\_long\_office\_household)。

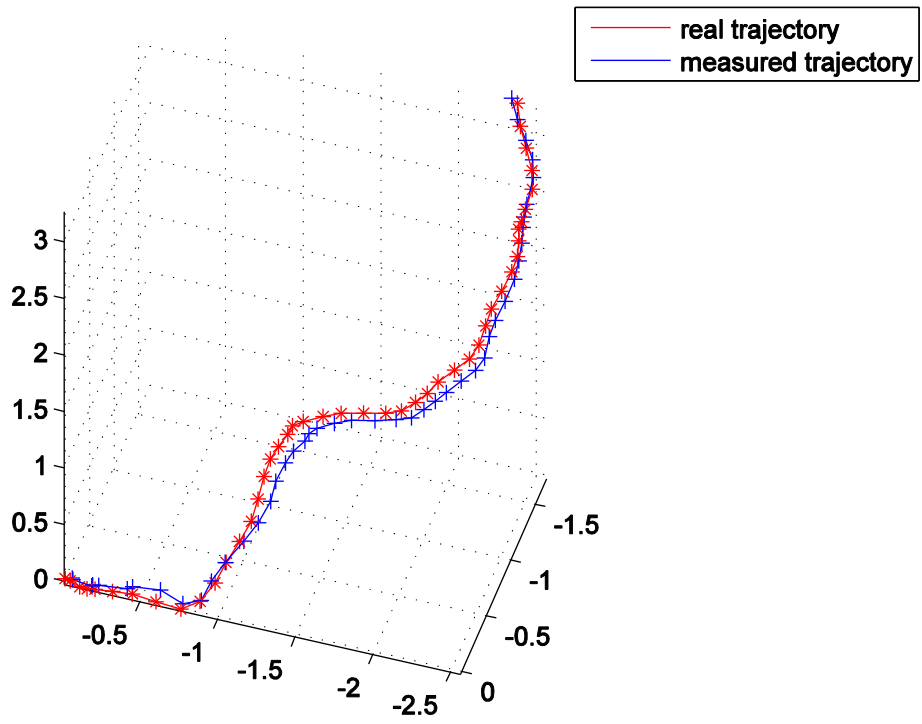
(Jurgen Sturm, Nikolas Engelhard, Felix Endres, Wolfram Burgard, and Daniel Cremers, A Benchmark for the Evaluation of RGB-D SLAM Systems, IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2012.)

总帧数	三对以上匹配平面	两对匹配平面	一对匹配平面
47	12	32	2

建图结果:



轨迹对比:



误差曲线:

